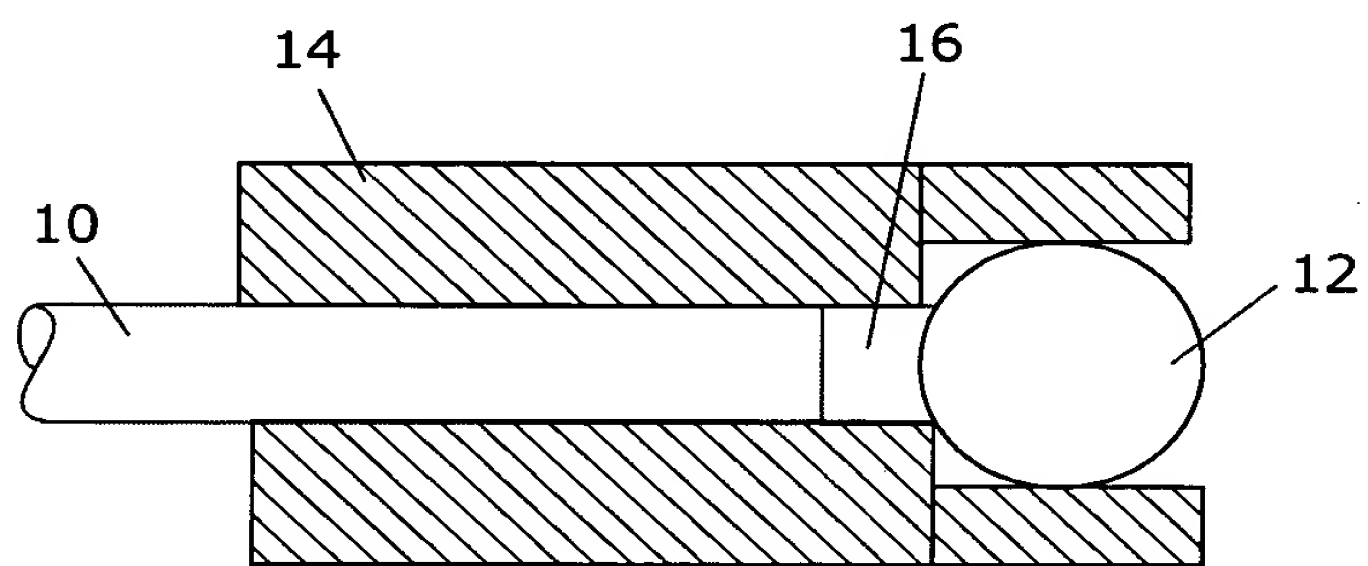
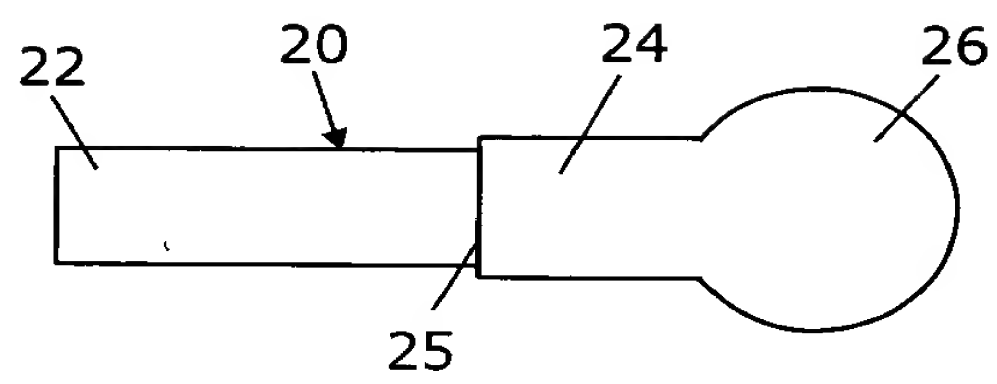


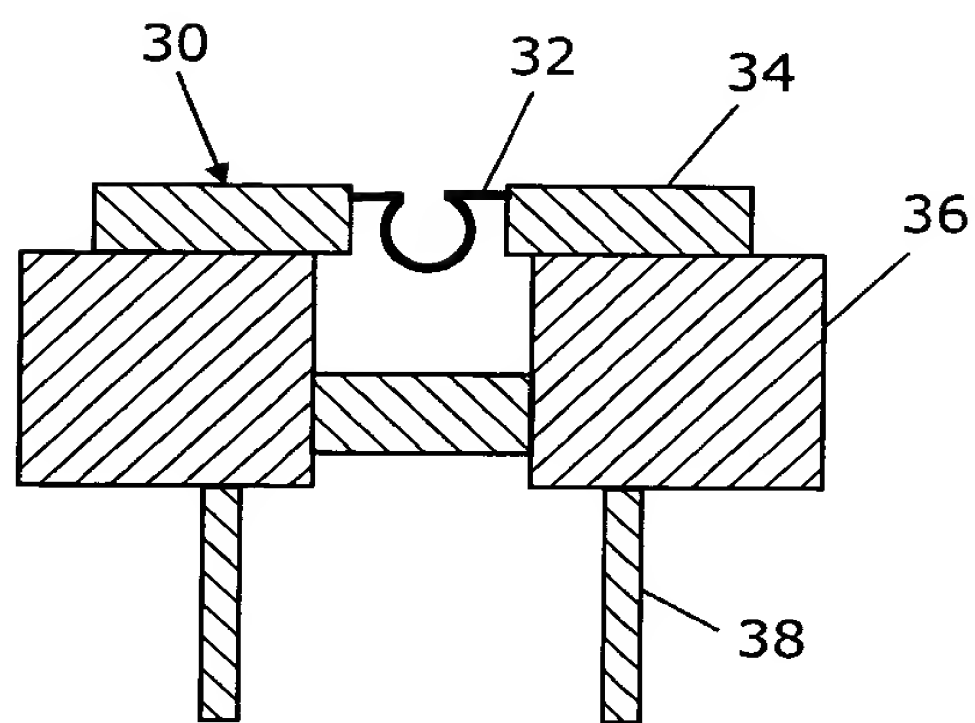
FIGURE 1



(Prior Art)
FIGURE 2



(Prior Art)
FIGURE 3



(Prior Art)
FIGURE 4

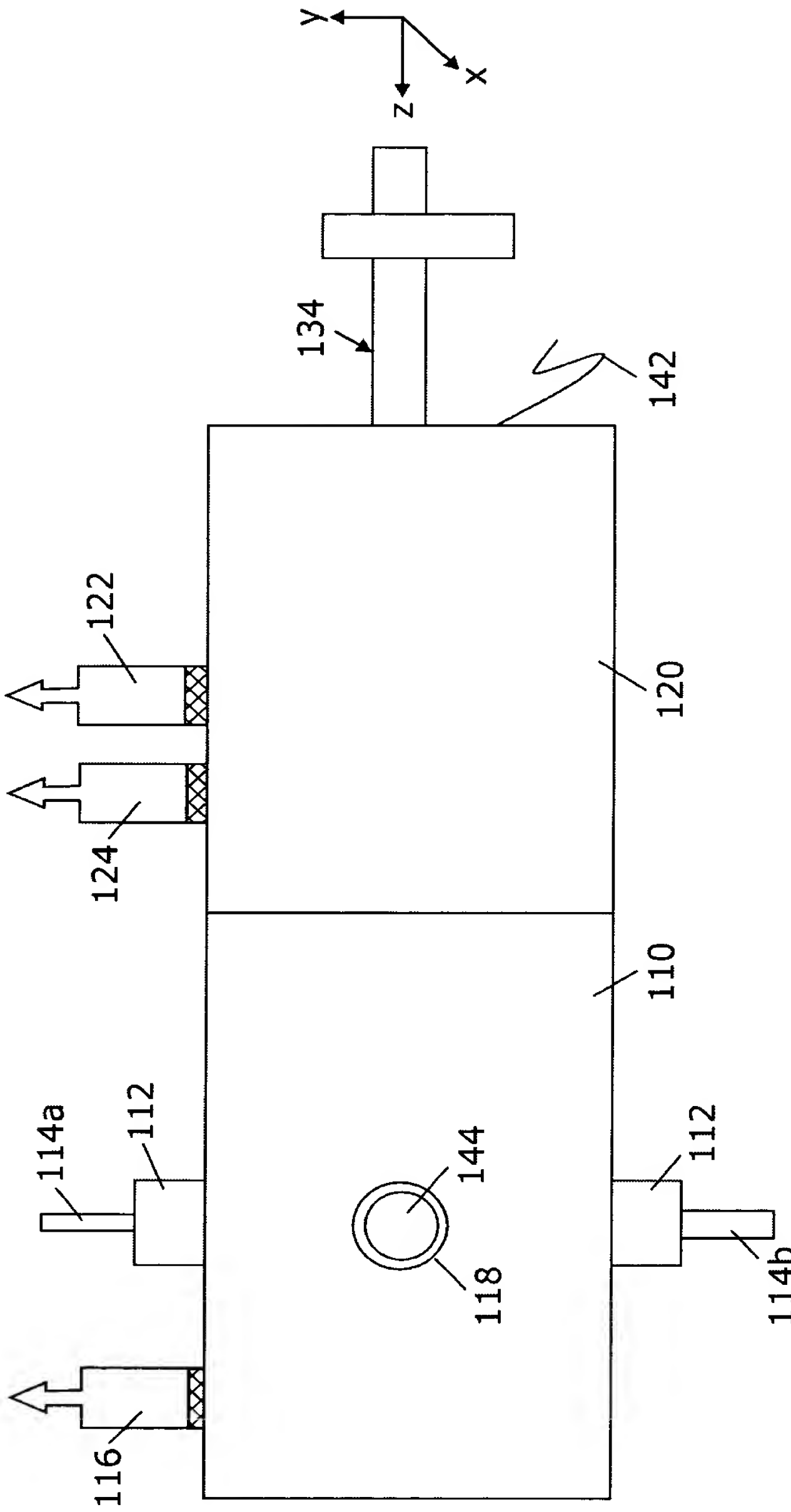
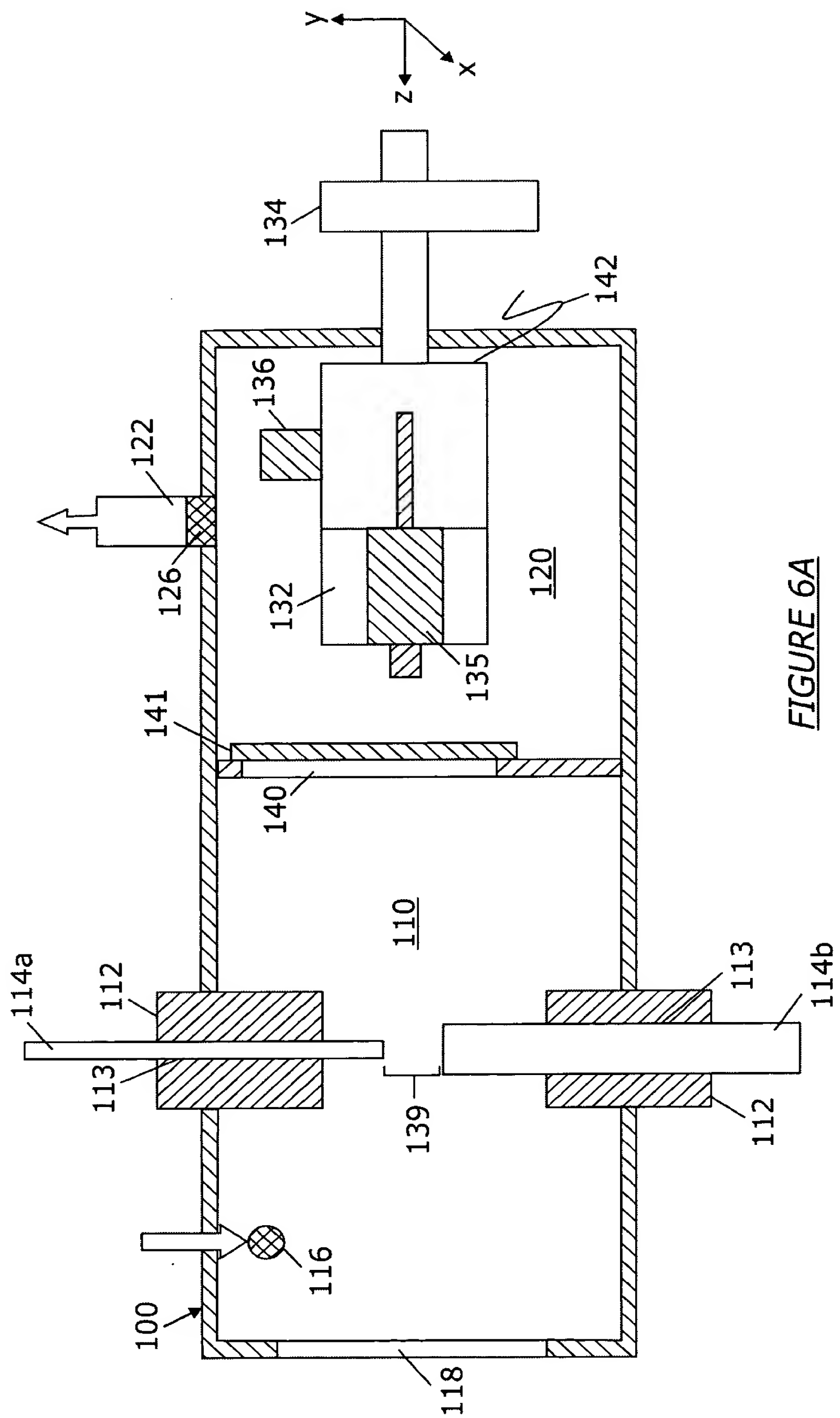


FIGURE 5



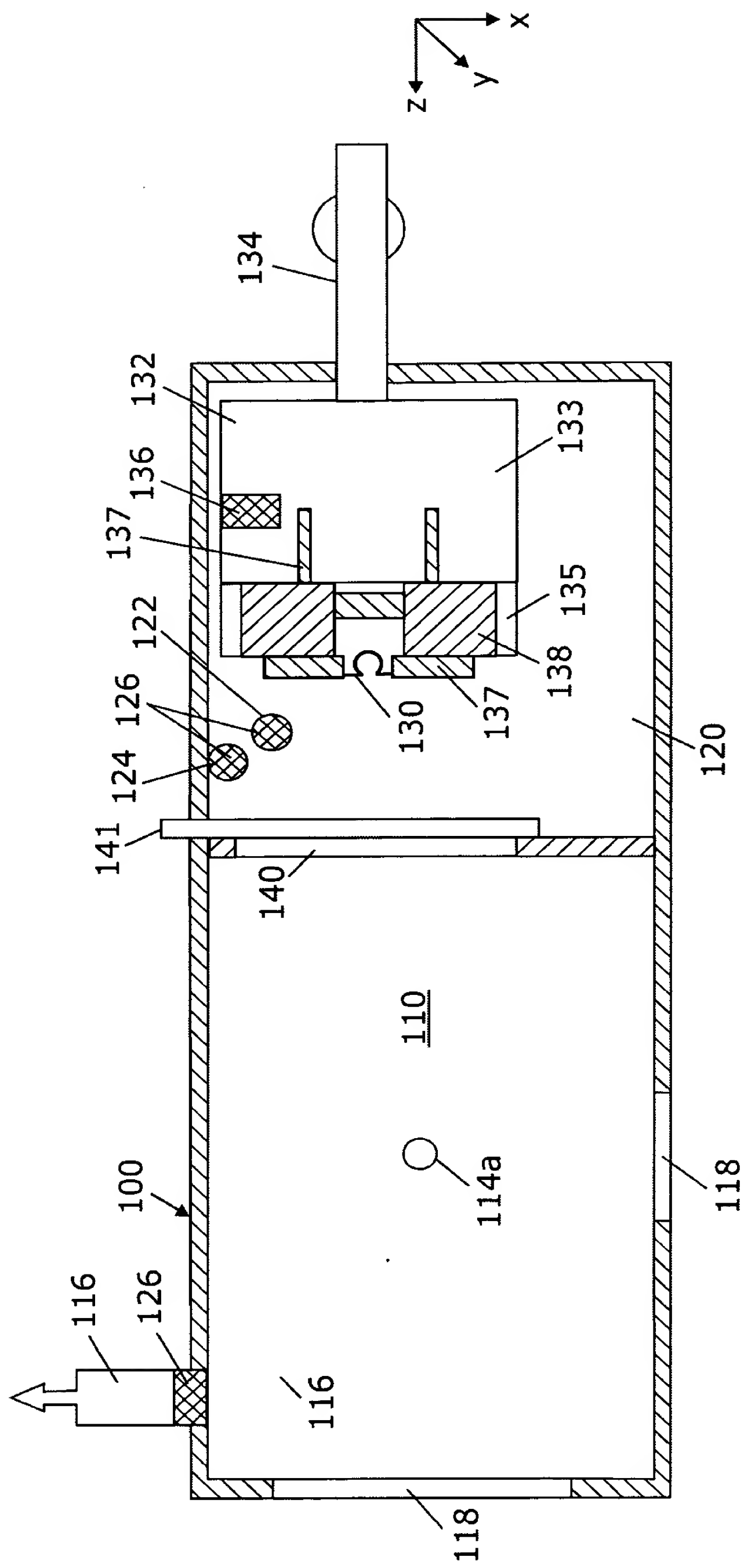


FIGURE 6B

FIG. 7 is a schematic diagram of a system 100 for processing a material 110. The system 100 includes a first processing unit 110 and a second processing unit 120. The first processing unit 110 includes a first input 116, a first output 114a, a first processing element 112, and a first control element 114b. The second processing unit 120 includes a second input 124, a second output 122, a second processing element 122, and a second control element 124. The first processing unit 110 is connected to the second processing unit 120 via a first connection 146. The first processing unit 110 also includes a first sensor 118 and a first actuator 144. The second processing unit 120 includes a second sensor 142 and a second actuator 134. A coordinate system with x, y, and z axes is shown.

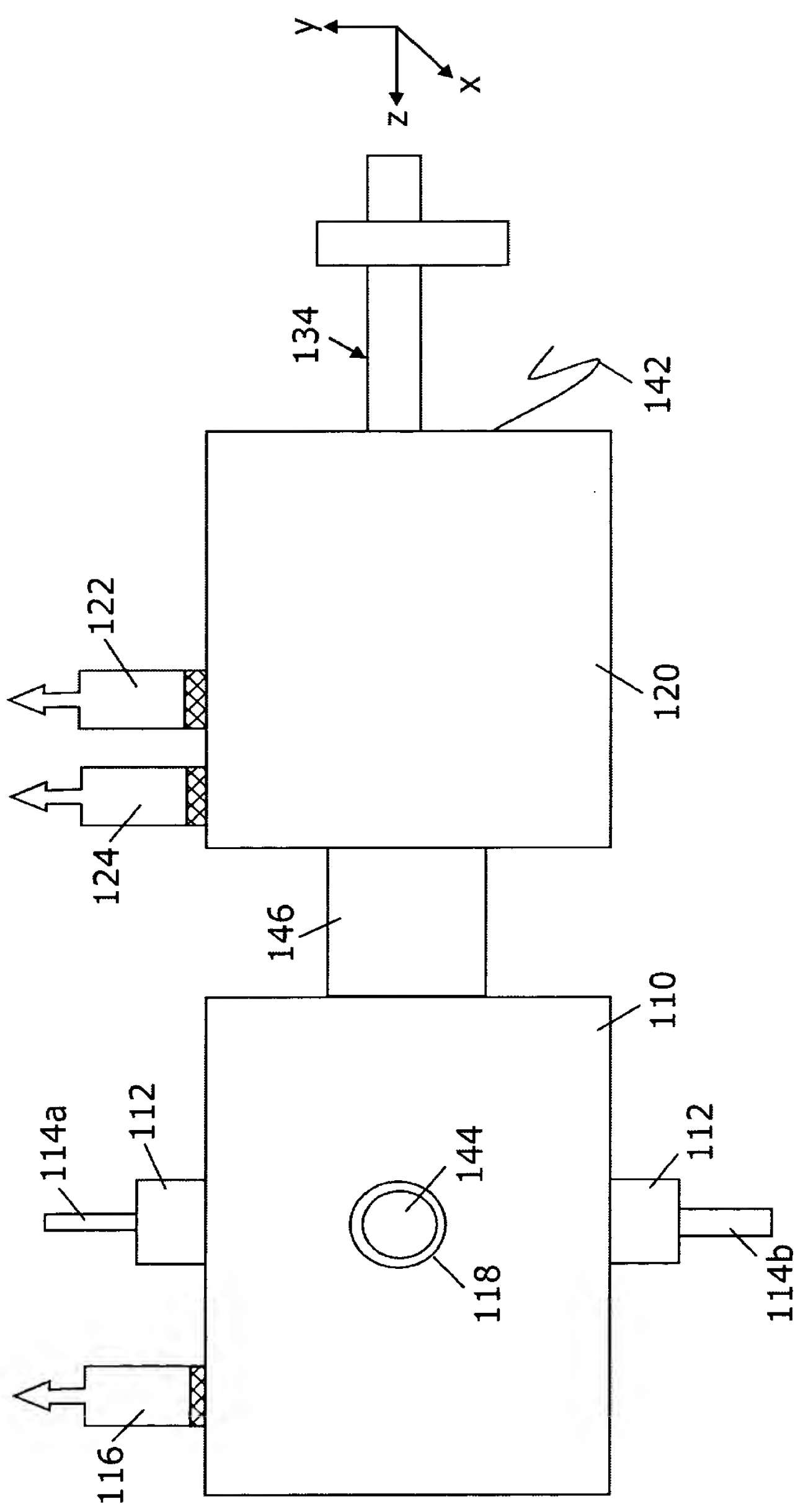


FIGURE 7

